



**Australian Centre for Space Engineering Research (ACSER)**  
in collaboration with  
**The Defence Science Technology Group,**  
**Department of Defence**

# **Biarri Point on Orbit Performance of the Namuru V32 GPS Receiver**

**Presented by**

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**at**

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# Biarri-Point Mission

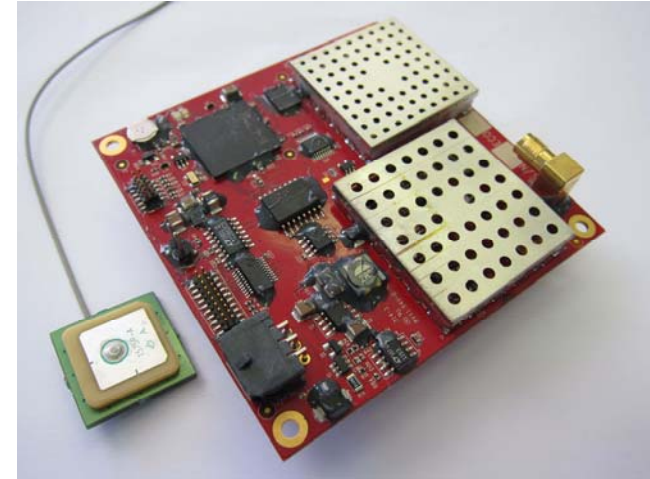
- Biarri is a Five Eyes cubesat mission that will do research into Space Situational Awareness (SSA)
- Biarri Point is being used to validate technologies to be used in future missions
- Deployed from the ISS in May 2017
- Australian contribution to the mission is an Australian & NZ designed & manufactured Namuru V32R3A GPS receiver



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# Namuru V32R3A GPS Receiver

- Hardware designed & manufactured in NZ
- Embedded C code firmware and Verilog FPGA designs developed & tested in Australia
- FPGA based GPS receiver consisting of a SmartFusion A2F500 SoC, a ProASIC3E A3PE1500 FPGA, 512k x 16 bit SRAM, 8Mb serial flash, GP2015 RF front end, ...
- Aquarius firmware designed to navigate in orbit
- Functional testing performed by ACSER, UNSW



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# First 100% Australian & NZ GPS in Space

- Namuru V32R3A is the first fully Australian & NZ designed and manufactured GPS receiver to successfully navigate and function in orbit
- The SigNav designed MG5001 (rebadged as a Phoenix GPS receiver by DLR and SGR05 by Surrey Satellite Technology Limited) employed firmware that was developed by their respective organisations and hence was not 100% Australian and NZ content

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# Namuru V32 On-Orbit Data Files

- Namuru V32 has been used to provide PVT information for Biarri Point
- Namuru V32 is the prime source of such information due to difficulties with the other GPS receiver that was installed on the spacecraft
- 5.4 MB of compressed ASCII data or 70 MB of uncompressed ASCII data has been provided by DST-Group to ACSER for analysis
- The data is in the NMEA ASCII sentences received from the GPS receiver supplemented with various time-tags and telemetry flags that have all been provided in the form of 'comma separated variables' (CSV) files
- After the unnecessary time-tags, telemetry and message duplications were stripped using an ad-hoc Python script, the data ended up being reduced to 17 MB of NMEA ASCII data provided by the GPS receiver
- Data files typically provided as date-hour sets covering 1 hour intervals

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# Namuru V32R3A Sentences 1

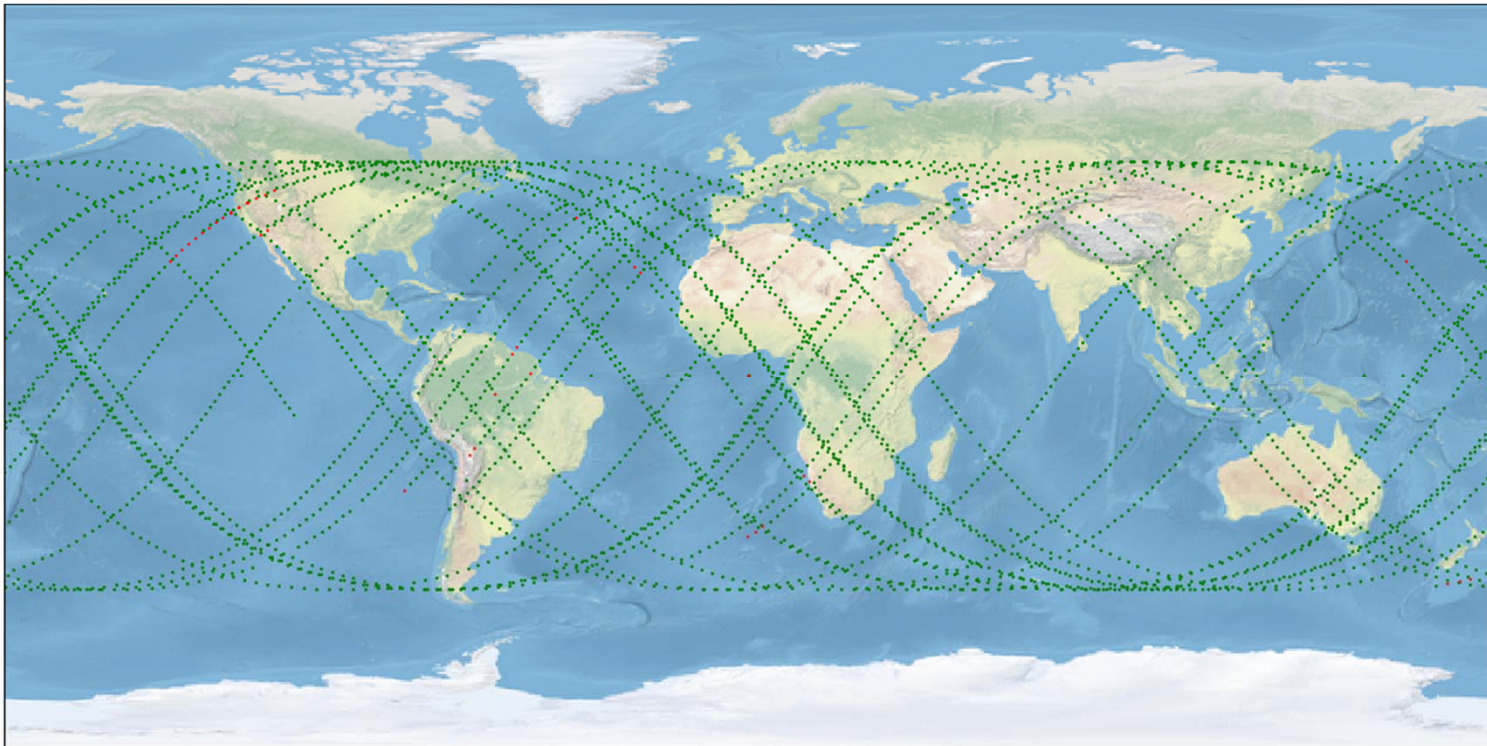
- Most data received from Namuru is in the form of XYZ sentences, with an example shown below
- \$PNSWR,XYZ,  
1,  
1979,420667.999999989,  
6610563.1,-1075491.1,963680.3,  
1540.467,4131.356,-5922.792,  
-4.2,0.467\*10
- \$PNSWRXYZHeader, Quality, Week, TOW,  
Xm, Ym, Zm, Xdotms, Ydotmps, Zdotmps, Tm, TDotmps \* Checksum
- Period of the output XYZ sentences range from the default 1 second to up to 30 seconds

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# Ground Tracks

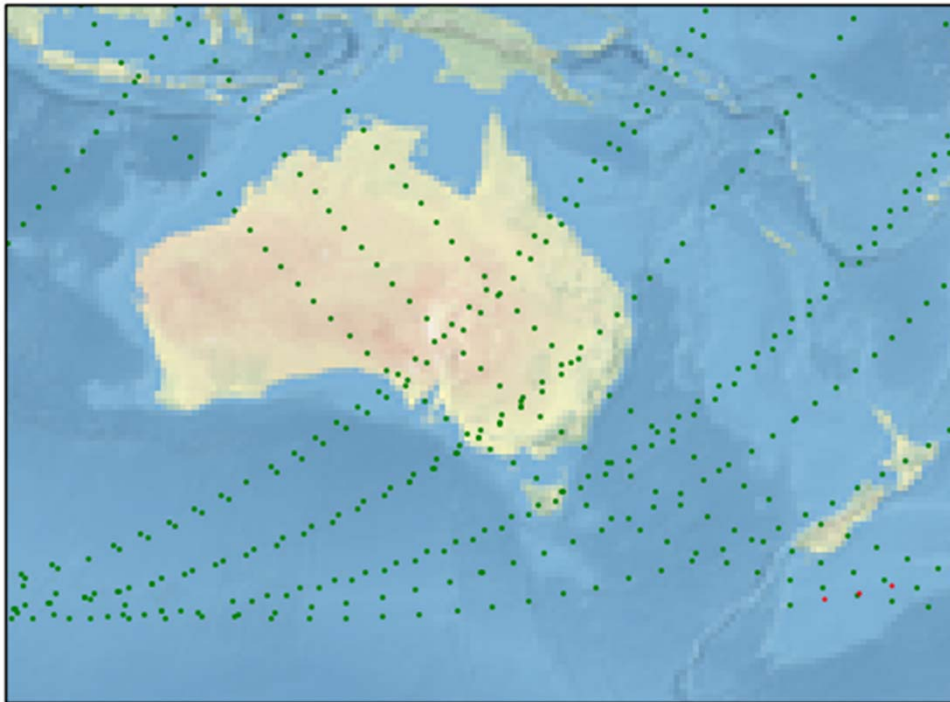
- Biarri Point Ground track data between 1-Nov-2017 to 15-Dec-2017  
(data sets are not continuous)



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# Ground Track Zoomed Over Australia

- Biarri Point Ground track data zoomed over Australia between 1-Nov-2017 to 15-Dec-2017 (same as previous plots)

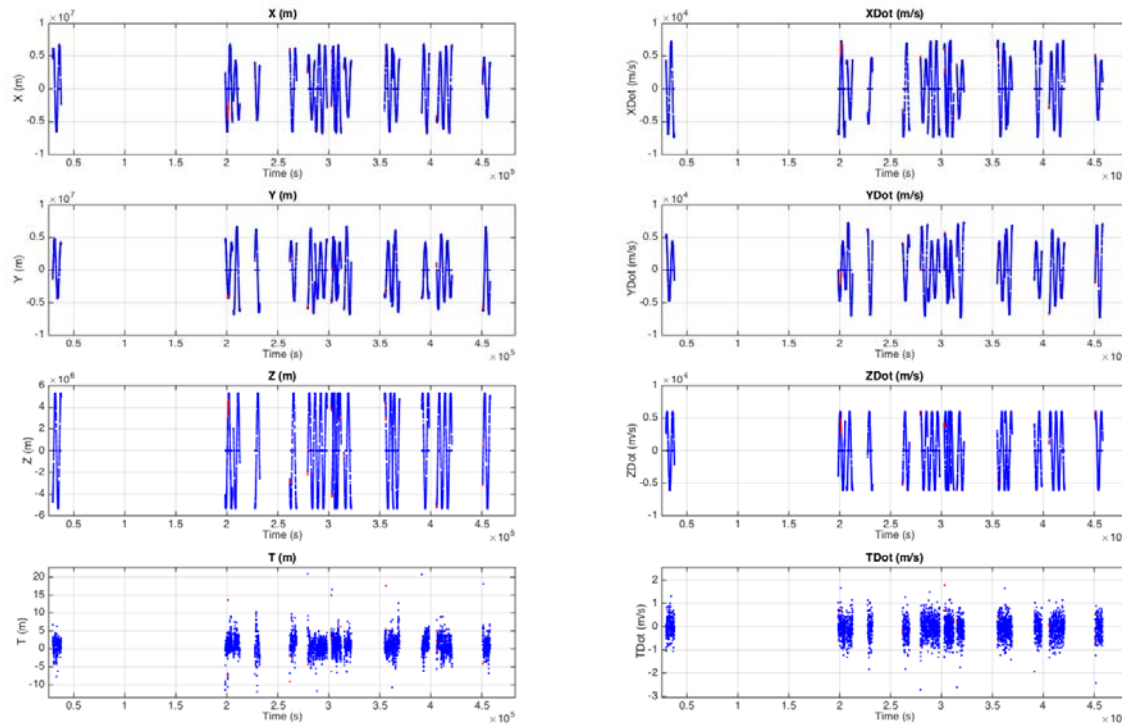


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# VC-TCXO Control

- Examination of the clock bias (T) and clock drift (Tdot) terms shows effectiveness of the clock disciplining
- Tdot within 1 m/s and T within 3 to 4 meters (3 sigma) → Working well



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# OBS Report Analysis

- Some logs contain OBS reports containing raw observables for each satellite being tracked
- Logs show receiver is being permitted to run for as long as 4 hours, but data is being polled every 60 seconds or so
- Good values for C/N0 being observed
- OBS reports also contain readings from an on-board temperature sensor – temperatures between 30 and 45 degrees were observed

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# Other Remarks

- Namuru is working well in orbit
- Possibility of doing some additional experiments, such as checking the effectiveness of the TLE estimation
- Examination of logs shows that some starts appear to be cold starts on account of the RTC super-capacitor discharging to a point at which the RTC stops running
  - Recommendation would be to switch the receiver on more often (perhaps every 6-8 hours or so) and let it navigate for a minute or two
  - This would recharge the supercapacitor and should result in most starts being warm starts

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